

# Diffusion Dynamics with Linear Drift Force

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# I. Introduction

$$\frac{\partial P}{\partial t} = \nabla \cdot (-f + D \cdot \nabla) P(q, t) \quad q, f \in \mathbb{R}^n \Leftrightarrow \dot{q}(t) = f(q, t) + \xi(t)$$

$f$  : drift force, rate function, force in over-damping limit  
 $D$  : diffusion matrix  $\langle \xi_i(t) \xi_j(t') \rangle = 2D_{ij} \delta(t-t')$

Equilibrium: steady state with detailed balance

$$P_{st} \propto e^{-\Phi_{st}}, \quad f = -D \cdot \nabla \Phi_{st}$$

$$\Rightarrow \begin{cases} j_{st} = (f - D \cdot \nabla) P_{st} = 0 \\ P(q'|q) e^{-\Phi_{st}(q)} = P(q|q') e^{-\Phi_{st}(q')} \end{cases}$$

zero steady state current  
detailed balance (DB)

Non-equilibrium

$$D^{-1} \cdot f = -\nabla \Phi + g, \quad g: \text{non-conservative}$$

$$\Rightarrow j_{st} \neq 0$$

breaking of detailed balance

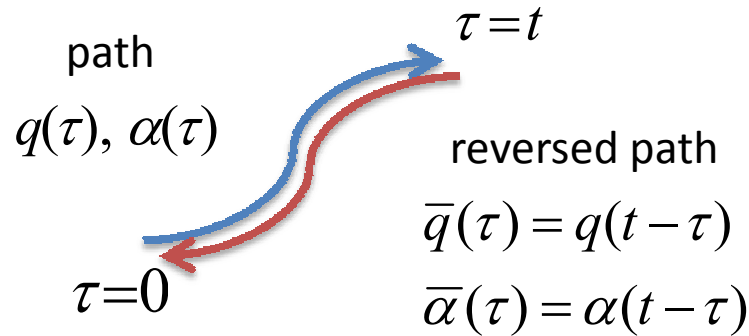
$D^{-1} \cdot f$  : (generalized) force       $g$  : NEQ-driving force

(i) non-conservative force

(ii) non-identical and correlated noise  $D \neq cI$

(iii) time-dependent parameter  $\Phi(q, \alpha(t))$

# I. Introduction



For Brownian dynamics,  $q = (x, p)$

$$\bar{x}(\tau) = x(t-\tau)$$

$$\bar{p}(\tau) = -p(t-\tau)$$

$$\bar{\alpha}(\tau) = \alpha(t-\tau)$$

Conditional probability  $\Pi[q; \alpha]$  for path  $q$  vs  $\Pi[\bar{q}; \bar{\alpha}]$  for reversed path  $\bar{q}$

$$\frac{\Pi[q]}{\Pi[\bar{q}]} = \exp\left(\int_0^t d\tau \dot{q}^T \cdot D^{-1} \cdot f\right)$$

$$= \exp\left(-\int_0^t d\tau \dot{q}^T \cdot (\nabla\Phi - g)\right)$$

$$\Pi[q]/\Pi[\bar{q}] = e^{-\Delta\Phi} \text{ (DB)}$$

$$= \exp\left(-\int_0^t d\tau \left(\frac{d\Phi}{dt} - \dot{q}^T \cdot g - \frac{\partial\Phi}{\partial t}\right)\right)$$

Potential (Energy)  $\Phi(q, \alpha)$

$$= \exp(-\Delta\Phi + W) \quad \text{Work production} \quad W = \int_0^t d\tau \left(\dot{q}^T \cdot g + \frac{\partial\Phi}{\partial t}\right)$$

$$= \exp(-Q) \quad \text{Heat production: } \Delta\Phi = W + Q \quad \text{1st law}$$

Inverse temperature :  $D \rightarrow \beta^{-1}D$ , measure for overall strength of noise

## II. Linear Drift Force

Linear drift force:

- almost exactly solvable case
- showing all natures of non-equilibrium

$$f = -F \cdot q \quad D^{-1} \cdot f = -(D^{-1}F) \cdot q$$

Symmetric + asymmetric  $D^{-1}F = G^s + G^a$

Equilibrium

$$G^a = 0, \quad \Phi_{st} = -\frac{1}{2} q^T \cdot D^{-1}F \cdot q$$

$$D^{-1}F = F^T D^{-1} \Rightarrow FD - DF^T = 0 \quad \text{condition for DB}$$

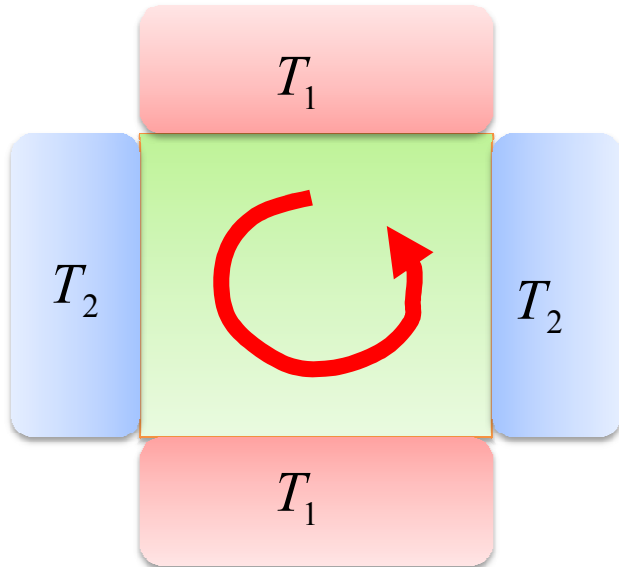
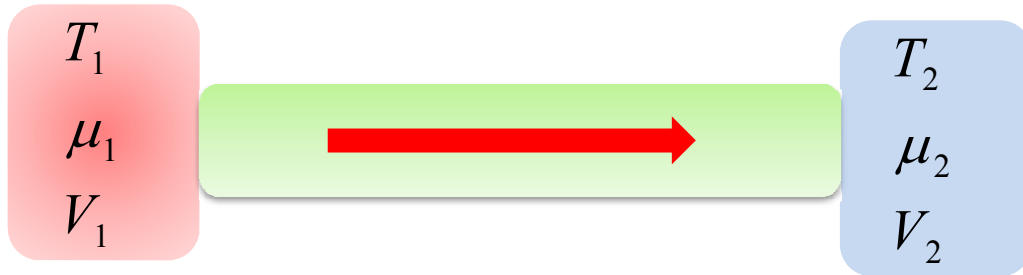
Non-equilibrium

Steady state ( Kwon-Ao-Thouless, PNAS, 2005)

$$\Phi_{st} = -\frac{1}{2} q^T \cdot (D + Q)^{-1} F \cdot q, \quad Q: \text{ anti-symmetric matrix}$$

$$FQ + QF^T = FD - DF^T \quad \text{breaking of DB}$$

$$J_{st} \propto -Q \cdot \nabla \Phi_{st} e^{-\Phi_{st}} \quad \text{circulation current around equi-probability surface}$$



$$D \propto \begin{pmatrix} T_1 & 0 \\ 0 & T_2 \end{pmatrix} \xrightarrow{\text{coord transf}} \begin{pmatrix} d_1 & c \\ c & d_2 \end{pmatrix}$$

$f : \text{non-conservative} \rightarrow F \neq F^T$



$$FD \neq F^T D \quad \text{NEQ}$$

$$FQ + QF = FD - DF^T \quad \text{anit-symm matrix}$$

$$J \propto -Q \cdot \nabla \Phi e^{-\Phi} \quad \text{circulation}$$

## II. Linear Drift Force

Non-equilibrium

$$G = D^{-1}F = G^s + G^a$$

$$G^s = \frac{1}{2}(D^{-1}F + F^T D^{-1}) + \delta G^s, \quad G^a = \frac{1}{2}(D^{-1}F - F^T D^{-1}) - \delta G^s$$

Energy :

$$\Phi = \frac{1}{2} q^T \cdot G^s \cdot q$$

NEQ-driving force :

$$g = -G^a \cdot q$$

Non-equilibrium work production

$$W[q] = -\int_0^t d\tau \dot{q} \cdot G^a \cdot q \quad (\dot{\alpha} = 0, \partial\Phi / \partial t = 0)$$

Need to find

$$P(q, t) = \int dq_0 P(q, t : q_0, t = 0) P_{in}(q_0)$$

$$P_{in}(q_0) = |\det(2\pi(G^s)^{-1})|^{-1/2} e^{-q^T \cdot G^s \cdot q / 2} \quad \text{Initial equilibrium pdf}$$

### III. Path Integral Formalism

Generating functional

$$Z[q(t); l; \lambda] = \int D[q] \exp\left( S[q] - \lambda W[q] + \int_0^t d\tau l(\tau)^T \cdot q(\tau) \right)$$

Action

$$S[q] = -\frac{1}{4} \int_0^t d\tau (q + Fq)^T \cdot D^{-1} \cdot (q + Fq)$$

Probability

$$P(q; t) = Z[q; l = 0; \lambda = 0] = |\det(2\pi A^{-1}(t))|^{-1/2} e^{-1/2 q^T \cdot A(t) \cdot q}$$

Expectation value

$$\langle F[q] \rangle = F \left[ \frac{\delta}{\delta l} \right] \hat{Z}[l] \Big|_{l \rightarrow 0}$$

exactly solvable

$$\hat{Z}[l] = \int dq(t) Z[q(t); l; \lambda = 0] = \exp\left( \frac{1}{2} \iint d\tau d\tau' l(\tau)^T \cdot \Gamma(\tau, \tau') \cdot l(\tau') \right)$$

### III. Path Integral Formalism

Probability distribution function for work production

$$P[W] = \int \frac{d\lambda}{2\pi} e^{iW\lambda + \ln \zeta(i\lambda)}$$

Only solvable  
Perturbatively in  $\lambda$

$$\zeta(\lambda) = \langle e^{-\lambda W} \rangle = \int dq(t) Z[q(t); l=0; \lambda] = \exp \left( -\frac{1}{2} \int_0^t d\tau \text{Tr} A^{-1}(\tau; \lambda) \Lambda(\lambda) \right)$$

with

$$\Lambda(\lambda) = \frac{1}{2} (F^T D^{-1} F - \tilde{F}^T D^{-1} \tilde{F}), \quad \tilde{F} = F - 2\lambda G^a$$



### III. Path Integral Formalism

Discretization

$$q(0) = q_0, q_1, \dots, q_{N-1}, q_N = q(t) \quad \Delta t = t / N$$

Path integral  $\rightarrow$  Gaussian integrals over  $\{q_i\}$

$$A^{-1}(t) = F^{-1} \left( D + Q - e^{-Ft} (D + Q) e^{-F^T t} \right) + e^{-Ft} A^{-1}(0) e^{-F^T t} \Rightarrow P(q, t) \propto e^{-1/2 q^T \cdot A(t) \cdot q}$$

$$\xrightarrow{t \rightarrow \infty} F^{-1} (D + Q)$$

Steady state (Kwon-Ao-Thouless, PNAS, 2005)

$$\langle q(t)^T \cdot q(t') \rangle = \Gamma(t, t') = \begin{cases} e^{-F(t-t')} A^{-1}(t'), & t > t' \\ A^{-1}(t') e^{-F^T(t'-t)}, & t' > t \end{cases}$$

$$\Phi_{st} = \frac{1}{2} q^T \cdot (D + Q)^{-1} F \cdot q$$

Expectation value of work production

$$\langle W \rangle = - \int_0^t d\tau \text{Tr} A^{-1}(\tau) G^a F \xrightarrow{t \rightarrow \infty} -t \text{Tr} F Q D^{-1} > 0$$

Entropy production rate

$$\langle \Delta \Phi \rangle = \langle W \rangle + \langle Q \rangle \xrightarrow{t \rightarrow \infty} \langle W \rangle \approx -\langle Q \rangle = t \langle \sigma \rangle$$

$$\Delta S_{tot} = \Delta S_{sys} + \Delta S_{res}, \quad \Delta S_{sys} = -\Delta \ln P \rightarrow \text{finite}, \quad \Delta S_{res} = -Q \approx W$$

$$\langle \sigma \rangle = -\text{Tr} F Q D^{-1}$$

rate of entropy piled up in the reservoir,  
approximate total entropy production rate

## IV. Example

Diffusion in 2 dimensions

$$q^T = (x, y)$$

$$F = \begin{pmatrix} k_1 & \kappa_1 \\ \kappa_2 & k_2 \end{pmatrix} \quad D = \begin{pmatrix} \alpha & \varepsilon \\ \varepsilon & \gamma \end{pmatrix}$$

$$FQ + QF^T = FD - DF^T$$

$$\Rightarrow Q = \frac{\hat{q}}{k_1 + k_2} \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix}, \quad \hat{q} = \varepsilon(k_1 - k_2) + \gamma\kappa_1 - \alpha\kappa_2$$

$t \rightarrow \infty$  limit

$$\langle \sigma \rangle = t^{-1} \langle W \rangle = \frac{\hat{q}^2}{\det D \cdot \text{Tr } F} > 0$$

2<sup>nd</sup> law of thermodynamics  
Valid for general stochastic process

$$\langle \sigma^2 \rangle_c = t^{-2} \langle W^2 \rangle = t^{-1} \frac{(2 \det F + (\text{Tr } F)^2) \hat{q}^2}{2 \det D \cdot \det A \cdot \text{Tr } F}$$

$$\langle W^n \rangle_c \propto t, \quad \langle \sigma^n \rangle_c \propto t^{-n+1}$$

## V. Summary and Future

1. Non-equilibrium is caused by

$$\begin{aligned} & \text{(i) non-identical/correlated noise } D \neq cI \quad \Rightarrow \quad D^{-1} \cdot f \neq -\nabla\Phi \\ & \text{(ii) non-conservative force } f \neq -\nabla V \end{aligned}$$

2. FT can be applied for general stochastic systems.

$$D^{-1} \cdot f = -\nabla\Phi + g$$

force  $D^{-1} \cdot f$       non-conservative force  $g$

energy  $\Phi$       work  $W = \int_0^t d\tau \dot{q} \cdot g$       heat  $\Delta\Phi - W$

3. Linear drift force as an analytically solvable case

$$\begin{aligned} f = -F \cdot q \quad \Rightarrow \quad & D^{-1} \cdot F = G^s + G^a \\ & \Phi = q^T \cdot G^s \cdot q / 2, \quad \dot{W} = -\dot{q}^T \cdot G^a \cdot q \end{aligned}$$

$$t^{-1} \langle W \rangle \xrightarrow{t \rightarrow \infty} \langle \sigma \rangle > 0, \quad t^{-2} \langle W^2 \rangle_c \xrightarrow{t \rightarrow \infty} \langle \sigma^2 \rangle_c \sim O(t^{-1})$$

## V. Summary and Future

### 4. Future interests

#### 4.1 Modification of FT in the presence of irreversible force

$$\dot{p} = -\gamma \cdot p / m + f(x, t) + g(x, p) + \xi, \quad g(\bar{x}, \bar{p}) = -g(x, p)$$

- Irreversible force might be unavoidable in impure materials
- Simple case in 1-dim: temperature-cooling (Kim and Qian, PRL, 2004; PRE, 2007)

$$g(x, p) = -\alpha \cdot p / m \Rightarrow \gamma^{\text{eff}} = \gamma + \alpha, \quad \beta^{\text{eff}} = (1 + \alpha / \gamma) \beta$$

- In high dimensions with  $\alpha$  : matrix for anisotropic media
  - no simple temperature-cooling
  - non-Maxwell distribution for velocity
  - modification of FT

#### 4.2 Simulation study for discrete variables such as Ising spins with updating rule

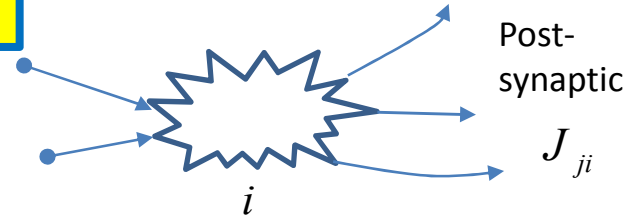
$$\frac{\Pi(A \rightarrow B)}{\Pi(B \rightarrow A)} = e^{-\beta \Delta Q} \quad \Delta Q: \text{ Heat production for transition } A \rightarrow B$$

# V. Future Topics

## 4.3 Neural network with asymmetric synaptic coupling

$$\sigma_i = \text{sgn}\left(\sum_j J_{ij} \sigma_j - h_i\right) \quad \text{for } J_{ij} \neq J_{ji}$$

Pre-synaptic  
 $J_{ik}$



$$J_{ij}^s = 1/2(J_{ij} + J_{ji}) \Rightarrow H = -\sum_{(i,j)} J_{ij}^s \sigma_i \sigma_j$$

$$J_{ij}^a = 1/2(J_{ij} - J_{ji}) \Rightarrow \Delta W = \sum_{i,j} J_{ij}^a (\Delta \sigma_i) \sigma_j$$

cf

$$\begin{cases} \Phi = 1/2 q^T \cdot G^s \cdot q \\ W = -\int_0^t d\tau \dot{q}^T \cdot G^a \cdot q \end{cases}$$

## 4.4 Modelling of experiments

Ex: additive colored (memory-dependent) noise (in granular exp)  
-> higher dimension with white noise